

Huang 2000-0221

$$\sum_{k=1}^K \omega_{ik} = \mu_i, 1 \leq i \leq N, \sum_{i=1}^N \omega_{ik} = \gamma_k, 1 \leq k \leq K.$$

2. The method according to claim 1 wherein at least one of said first and second mixture probability distribution functions includes a Gaussian Mixture Model.

3. The method according to claim 1 wherein the element distance between the first and second probability distance functions is a Kullback Leibler Distance.

4. The method of claim 1 wherein the first and second probability distribution functions are Gaussian mixture models derived from audio segments.

5. A computer program embedded in a storage medium for computing a distance measure between first and second mixture type probability distribution functions,

$G(x) = \sum_{i=1}^N \mu_i g_i(x)$, and $H(x) = \sum_{k=1}^K \gamma_k h_k(x)$, pertaining to audio data, the improvement comprising a software module that evaluates said distance measure in accordance with equation:

$$D_M(G, H) = \min_{w=\{\omega_{ik}\}} \sum_{i=1}^N \sum_{k=1}^K \omega_{ik} d(g_i, h_k),$$

where $d(g_i, h_k)$ is a function of distance between a component, g_i , of the first probability distribution function and a component, h_k , of the second probability distribution function

where

$$\sum_{i=1}^N \mu_i = 1 \text{ and } \sum_{k=1}^K \gamma_k = 1,$$

and

$$\omega_{ik} \geq 0, 1 \leq i \leq N, 1 \leq k \leq K,$$

and

$$\sum_{k=1}^K \omega_{ik} = \mu_i, 1 \leq i \leq N, \sum_{i=1}^N \omega_{ik} = \gamma_k, 1 \leq k \leq K.$$

Huang 2000-0221

6. The computer program according to claim 5 wherein at least one of said first and second mixture probability distribution functions includes a Gaussian Mixture Model.

7. The computer program according to claim 5 wherein the element distance between the first and second probability distance functions includes Kullback Leibler Distance.

8. The computer program of claim 5 wherein the first and second probability distribution functions are Gaussian mixture models derived from audio segments.

9. A computer system for computing a distance measure between first and second mixture type probability distribution functions, $G(x) = \sum_{i=1}^N \mu_i g_i(x)$, and

$H(x) = \sum_{k=1}^K \gamma_k h_k(x)$, pertaining to audio data comprising:

memory for storing said audio data;

a processing module for deriving one of said mixture type probability distribution functions from said audio data; and

a processing module for evaluating said distance measure in accordance with

$$D_M(G, H) = \min_{w=\{\omega_{ik}\}} \sum_{i=1}^N \sum_{k=1}^K \omega_{ik} d(g_i, h_k),$$

where $d(g_i, h_k)$ is a function of the distance between a component, g_i , of the first probability distribution function and a component, h_k , of the second probability distribution function,

where

$$\sum_{i=1}^N \mu_i = 1 \text{ and } \sum_{k=1}^K \gamma_k = 1,$$

and

$$\omega_{ik} \geq 0, 1 \leq i \leq N, 1 \leq k \leq K,$$

and

Huang 2000-0221

see B, enclosed

$$\sum_{k=1}^K \omega_{ik} \mu_i, 1 \leq i \leq N, \sum_{i=1}^N \omega_{ik} = \gamma_k, 1 \leq k \leq K.$$

10. The computer system according to claim 9 wherein at least one of said first and second mixture probability distribution functions includes a Gaussian Mixture Model.
11. The computer system according to claim 9 wherein the element distance between the first and second probability distance functions includes Kullback Leibler Distance.
12. The computer system of claim 9 wherein the first and second probability distribution functions are Gaussian mixture models derived from audio segments.

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13. A method for computing a distance measure between a mixture-type-probability distribution function $G(x) = \sum_{i=1}^N \mu_i g_i(x)$, where μ_i is a weight imposed on component, $g_i(x)$, and a mixture type probability distribution function $H(x) = \sum_{k=1}^K \gamma_k h_k(x)$, where γ_k is a weight imposed on component h_k comprising the steps of:
- computing an element distance, $d(g_i, h_k)$, between each g_i and each h_k where $1 \leq i \leq N, 1 \leq k \leq K$,
- computing an overall distance, denoted by $D_M(G, H)$, between the mixture probability distribution function G , and the mixture probability distribution function H , based on a weighted sum of the all element distances,

see B,

$$\sum_{i=1}^N \sum_{k=1}^K \omega_{ik} d(g_i, h_k),$$

wherein weights ω_{ik} imposed on the element distances $d(g_i, h_k)$, are chosen so that the overall distance $D_M(G, H)$ is minimized, subject to

$$\omega_{ik} \geq 0, 1 \leq i \leq N, 1 \leq k \leq K$$